

**TUNER OF THE TYPE HAVING ZERO INTERMEDIATE FREQUENCY
AND CORRESPONDING CONTROL PROCESS**

Field of the Invention

The present invention relates to the decoding of a radio frequency transmission channel conveying coded digital information, and applies advantageously, but not limitingly, to satellite-based digital telebroadcasting. Satellite-based digital telebroadcasting may be defined in the Digital Video Broadcasting-satellite (DVB-S) European specification based on the MPEG compression standards, and uses quadrature digital modulation to convey the information, for example. The invention thus relates more particularly to tuners, and in particular, to a tuner of the type having a zero intermediate frequency, such as, for example, those incorporated into satellite receivers with decoders for compressed image data, otherwise known as set-top boxes.

Background of the Invention

The television signals originating from a satellite are amplified and converted into a predetermined frequency band, typically 950 MHZ to 2,150 MHZ, by way of a parabolic dish and a low-noise

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especially the controlled-gain amplification stages as well as the mixers of the frequency transposition stage.

Furthermore, current approaches provide for
5 the low-noise input amplifier and the wide band filters to be made external from the chip containing the controlled-gain amplifying stage as well as the frequency transposition stage. These filters, whose cut-off frequencies can be tailored by selecting the
10 desired channel, are then embodied as discrete components, such as varicap diodes. Such components, are of an overly large size which is incompatible with a fully integrated embodiment of the tuner.

Summary of the Invention

15 In view of the foregoing background, an object of the present invention is to provide a tuner which can be fully embodied in an integrated fashion on a silicon substrate, while avoiding saturation of the various elements of the tuner.

20 The invention therefore proposes a process for controlling a tuner of a type having a zero intermediate frequency. The tuner comprises an analog block containing a first attenuator/controlled-gain amplifier stage connected upstream of a frequency
25 transposition stage containing baseband filters, and a digital block connected to the analog block by an analog/digital conversion stage.

According to a general characteristic of the invention, the control process comprises a phase of
30 initialization in which the overall mean power of the entire signal received by the tuner is calculated. This overall calculated power is compared in the

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digital block with a first predetermined reference value corresponding to a maximum power desired at a predetermined location of the analog block. This predetermined location may be at the input of the

5 mixers of the frequency transposition stage, for example. The gain of the first attenuator/amplifier stage is then adjusted to minimize the deviation between the overall calculated power and the reference value. The control process according to the invention

10 furthermore comprises a phase of normal operation in which one of the channels of the signal received is selected, while the gain of the first attenuator/amplifier stage is fixed.

In a general manner, it is possible to

15 calculate the overall mean power of the entire signal received by the tuner on the basis of any signal available in the analog block upstream of the first filter of this analog block. Thus, when the mixers of the frequency transposition stage are not equipped with

20 filters, the first filtering encountered in the analog block is the baseband filter.

In this case, it would therefore be possible to use any signal tapped off upstream of this baseband filter. Generally, the mixers used in a frequency

25 transposition stage of a tuner intrinsically include a filter. In this case, an analysis of the overall power of the signal received is carried out before the mixers. These elements are the last of the analog reception chain receiving all the power from various

30 channels. It is preferable, in particular, to use the signal available between the output of the first attenuator/amplifier stage and the input of the frequency transposition stage, for design reasons.

According to an implementation of the process according to the invention, the calculation of the overall mean power of the entire signal received is performed in the digital block, i.e., downstream of the analog/digital conversion stage. This calculation of the overall mean power then comprises, for example, a calculation of the modulus of the sampled signal as well as a numerical integration over a certain number of samples, typically 2^{21} . It would be possible as a variation to provide an integrating analog filter in the analog block intended to perform the averaging of the analog signal on the basis of which one wishes to calculate the overall mean power.

Next, the output signal from the filter (voltage), representative of the overall mean power of the signal received, would then be sampled in the analog/digital conversion stage. In theory, it would be necessary to use only a single sample to perform the comparison with the reference value. However, in practice, this comparison would be performed with a mean value calculated over a very limited number of samples, such as three or four, for example.

The process according to the invention is also particularly advantageous when the analog block of the tuner furthermore comprises a second controlled-gain amplifier stage connected downstream of the baseband filter. In this case, according to one mode of implementation of the process, the mean power of the selected channel is calculated in the phase of normal operation. This calculated mean power of the channel is compared in the digital block with a second predetermined reference value corresponding to a maximum desired channel power at the input of the

drawback of this approach resides in the fact that one then possesses only a single information source relating to the reception power on the tuner, and that this information is located at the output of the analog chain. Also, this information is already filtered and therefore possesses only a part of the input signal, namely the desired channel and possibly the adjacent channels. The accuracy of adjustment of the various controlled-gain amplifiers is therefore less accurate than that used in the present invention. Two different calculations of power are used according to the present invention, i.e., in the initialization phase and in the phase of normal operation, so as to independently adjust the gains of the two controlled-gain amplifying stages.

Furthermore, if it is now assumed that a spurious reception spike is located in the vicinity of the selected channel. The latter will have a strong influence in the calculation of the power performed at the end of the analog chain in the prior art approaches. Consequently, the gain of the first amplifier stage will tend to be minimized to avoid saturation of the subsequent elements. This thereby leads to an increase in the gain of the second amplifier stage to obtain the maximum dynamic range at the input of the analog/digital conversion stage.

In the process according to the invention, the power of the spurious spike is diluted within the overall power of the signal received. This will lead, in the initialization phase, to the adjusting of the first amplifier stage to have a slightly higher gain than in the prior art. Therefore, in the phase of normal operation, the channel power calculation

performed at the output of the analog chain will lead to the adjusting of the gain of the second amplifier stage to have a slightly lower gain than in the prior art. A larger margin is therefore obtained with
5 regards to adjusting the gain of the second amplifier together with better balancing in the control of the gains.

The subject of the present invention is also a tuning device of the type having a zero intermediate
10 frequency comprising a signal input, an analog block containing a first attenuator/controlled-gain amplifier stage connected between the signal input and a frequency transposition stage containing a baseband filter, and a digital block connected to the analog
15 block by an analog/digital conversion stage.

According to a general characteristic of the invention, the device comprises

- controllable means for signal routing incorporated into the analog block for possessing an
20 input terminal connected to the signal input, a first output terminal connected to the input of the baseband filter, and a second output terminal connected directly to the input of the analog/digital conversion stage,

- first means of calculation, connected to
25 the second output terminal of the routing means, and able to calculate the overall mean power of the entire signal received by the tuner,

- first means of comparison, incorporated into the digital block, and able to compare this
30 overall calculated power with a first predetermined reference value corresponding to a maximum power desired at a predetermined location of the analog block,

- first means of adjustment able to adjust the gain of the first attenuator/amplifier stage as a function of the result of the comparison, and

- means of control able in a phase of
- 5 initialization to control the routing means in such a way as to connect their input terminal to their second output terminal to minimize the deviation between the overall calculated power and the first reference value, and in a phase of normal operation in the course of
- 10 which a channel of the signal received is selected, to control the routing means to connect their input terminal to their first output terminal, with the gain of the first attenuator/amplifier stage being fixed.

According to one embodiment of the device,

15 the analog block of the tuner furthermore contains a second controlled-gain amplifier stage connected downstream of the baseband filter. The tuner thus also comprises:

- second means of calculation connected to
- 20 the output of the baseband filtering means and able to calculate in the phase of normal operation the mean power of the selected channel,

- second means of comparison incorporated into the digital block and able to compare this mean

25 calculated channel power with a second predetermined reference value corresponding to a maximum channel power desired at the input of the analog/digital conversion stage, and

- second means of adjustment able to adjust
- 30 the gain of the second amplifier stage to minimize the deviation between the calculated channel power and the second reference value.

Preferably, the signal routing means are disposed between the output of the first attenuator/amplifier stage and the input of the frequency transposition stage. The digital block can
5 incorporate the first means of calculation. The device according to the invention is advantageously embodied entirely in an integrated fashion on a semiconductor substrate.

The invention also provides a receiver for
10 satellite digital television signals, comprising a tuning device such as that defined above.

Brief Description of the Drawings

Other advantages and characteristics of the invention will be apparent on examining the detailed
15 description of non-limiting embodiments and modes of implementation and, of the appended drawings, in which:

Figure 1 is a schematic diagram of the internal architecture of a frequency tuning device according to the present invention; and

20 Figure 2 is a schematic flow chart of the main steps of a control process according to the present invention.

Detailed Description of the Preferred Embodiments

In Figure 1, the reference RDS denotes a
25 satellite receiver/decoder (set-top box) connected to a parabolic antenna ANT picking up digital television signals for receiving and decoding these signals. This receiver RDS comprises, at the front end, a tuning device or tuner TZ intended for selecting the desired
30 channel from the set of channels present in the signal received at the signal input ES0 of this tuner.

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The output of the stage ETA1 is connected to the input terminal BE of a signal routing means formed by a multiplexer MUX1 controlled by a control signal SC. This multiplexer MUX1 comprises a first output
5 terminal BS1 linked to the two mixers MX1 and MX2 of the frequency transposition stage.

These two mixers MX1 and MX2 also receive, in a conventional manner, two quadrature mixing signals from a frequency synthesizer SYT, for example. The
10 frequency of each of the two mixing signals is identical and corresponds to the frequency of the selected channel. The frequency synthesizer SYT is controlled by a selection signal from a selection input ES2 connected to an I²C bus according to terminology
15 readily known by one skilled in the art. Furthermore, the frequency synthesizer is driven by a reference clock signal received on an input ES1 and originating from a quartz QT.

The two processing paths connected to the
20 outputs of the two mixers MX1 and MX2 are quadrature paths, named I and Q respectively according to standard terminology readily known by one skilled in the art. The I path represents the in-phase signal, while the Q path represents the quadrature signal.

25 The mixers MX1 and MX2 are equipped at the output with low-pass filters, the cut-off frequency of which is on the order of 150 to 250 MHz. The output signal from the two mixers MX1 and MX2 is therefore a signal centered about the frequency 0 MHz, extending
30 over a frequency band of 150 to 250 MHz and including the selected channel as well as the immediately adjacent channels. The width of a channel is on the order of 40 MHz for high definition digital television

signals. The two baseband filters FBB1 and FBB2, which follow the two mixers MX1 and MX2, have a passband on the order of 40 MHZ. Consequently, a filtered signal comprising the selected channel only is recovered at the output of these two baseband filters.

The two baseband filters are followed by a second controlled-gain amplifying stage formed by two controlled-gain amplifiers AGC1 and AGC2. The outputs of the two amplifiers AGC1 and AGC2 are respectively connected to the input terminals BE3 and BE30 of two other multiplexers MUX2 and MUX20 likewise controlled by the control signal SC.

The multiplexer MUX1 also comprises a second output terminal BS2 connected directly to the other two input terminals BE2 and BE20 of the other two multiplexers MUX2 and MUX20. This direct connection path therefore shunts any means of filtering the overall signal. In this instance the filters are present at the input of the mixers MX1 and MX2 as well as the baseband filters FBB1 and FBB2. This direct connection makes it possible, as will be seen in greater detail below, to calculate the overall power of the entire signal received.

The two output terminals BS3 and BS30 of two multiplexers MUX2 and MUX20 are respectively connected to the two inputs of two analog/digital converters CAN1 and CAN2 intended for sampling the analog signals received at their input at a sampling frequency, for example, on the order of 150 MHZ. These two analog/digital converters CAN1 and CAN2 mark the boundary between the analog block BAN of the tuner BZ and the digital block BNM of this tuner.

- The two in-quadrature digital signals I and Q delivered by the analog/digital converters are processed in a calculation block MCL which will determine the power of this signal (I, Q) by calculating, for example, the modulus thereof. A simplified way of calculating the modulus of the signal in the block MCL is provided by formula (1):

$$\text{Modulus (I,Q)} = \text{Max}(\text{abs(I)}, \text{abs(Q)}) + \frac{1}{2} \text{Min}(\text{abs(I)}, \text{abs(Q)}) \quad (1)$$

- 10 In this formula, Max denotes the maximum value, Min denotes the minimum value and abs denotes the absolute value.

- As will be seen in greater detail below, according to the phases of operation of the tuner, the input terminal of the multiplexer MUX1 can be connected either to its first output terminal BS1, or to its second output terminal BS2. Likewise, the output terminals BS3 and BS30 of the multiplexers MUX2 and MUX20 can be correspondingly linked to the output terminals BE2 and BE20 or BE3 and BE30. When a direct connection is effected between the output of the stage ETA1 and the analog/digital converters CAN1 and CAN2, the two signals I and Q are in fact identical signals and are not in-quadrature signals.

- 25 Formula (1) above for calculating the modulus therefore simplifies and becomes formula (2) below in which S denotes the signal delivered by the output terminal BS2 of the multiplexer MUX1.

$$\text{Modulus (S)} = \text{Max}(\text{abs(S)}) + \frac{1}{2} \text{Min}(\text{abs(S)}) \quad (2)$$

When the output of the stage ETAl is connected to the converter CAN1 and CAN2 by way of the frequency transposition stage and of the baseband filters, the two signals I and Q are indeed two in-quadrature signals. The output of the calculation block MCL is linked to a multiplexer MUX4. One of the outputs of which is linked to a subtractor ADD1, and the other output of which is linked to a subtractor ADD2.

When one wishes to calculate the overall mean power of the entire signal received, the multiplexer MUX4 is controlled to deliver the signal arising from the calculation block MCL to the subtractor ADD1. This subtractor ADD1 furthermore receives on its second input a first reference value stored, for example, in a register or a memory MM1. This first reference value corresponds to a maximum power desired at a predetermined location of the analog block, for example, at the input of the mixers of the frequency transposition stage. By way of indication, it will be possible to fix this first reference value at -10 dBm, thereby making it possible to avoid saturation of the elements of the analog block, for example.

Each sample delivered by the calculation block MCL is representative of the instantaneous power of the signal received at the input of this block MCL. The subtractor ADD1 compares the instantaneous power of each sample with the first reference value. These successive comparison values are then temporally integrated in an integrator with programmable coefficients FIR1.

The integration is performed over a sliding window of 2^{21} samples and the output of the integrator

therefore provides the deviation between the overall mean power of the entire signal received and the first reference value. Consequently, it would also be possible to perform the integration at the output of the block MCL to calculate the mean power of the overall signal, then to subtract the reference value from this mean value. The subtractor would in this case be placed downstream of the integrator.

The output from the integrator FIR1 is then delivered to means for adjusting the gain of the stage ETA1. These adjusting means comprise, for example, a reference table which is decoded by the output of the integrator and will deliver a digital word whose value will make it possible to control the breaker of the attenuator block ATN and to fix the gains of the two amplifiers AGCA and AGCB.

When the input of the multiplexer MUX4 is connected to its other output, which is the one linked to the subtractor ADD2, it will be possible to calculate the mean power of the selected channel and to adjust the gain of the two controlled-gain amplifiers AGC1 and AGC2. In this regard, a register or memory MM2 contains a second reference value corresponding to a maximum channel power desired at the input of the analog/digital conversion stage to obtain the maximum dynamic range at the input of this stage.

This second reference value can be taken equal to 7 dB. The subtractor ADD2 then calculates the deviation between the instantaneous power of each sample of the selected channel and this second reference value. These deviations are then integrated in an integrator FIR2 having a structure similar to that described for the integrator FIR1. Likewise, by

analogy with what was described above for the integrator FIR1, the indicator FIR2 decodes a second reference table TB2 which makes it possible to adjust the gain of the amplifiers AGC1 and AGC2.

5 The tuner TZ furthermore comprises control means MCM, which may be embodied in hard-wired form or within a microcontroller, for example. The control means MCM is intended for delivering, in particular, the control signal SC making it possible to switch the
10 various multiplexers of the tuner.

 Finally, in a conventional manner, the receiver RDS comprises a block DM receiving the two signals I and Q and is capable of performing the subsequent conventional processing operations of
15 demodulation and of channel decoding. Demodulation includes QPSK or 8-PSK demodulation according to terminology well known by one skilled in the art. Channel decoding includes Viterbi decoding, deinterlacing, Reed-Solomon decoding and deshuffling
20 for delivering a stream of packets FM which will be decoded in a source decoding block in accordance with the MPEG standard, for example.

 The manner of operation of the tuner according to the invention will now be described in
25 greater detail with reference to Figure 2. Upon turning on the tuner, or upon a change of channel, the control means MCM positions the multiplexers MUX1, MUX2 and MUX20 to allow a direct connection between the output of the amplifying stage ETAl and the
30 analog/digital converters. Likewise, the multiplexer MUX4 is positioned to link the block MCL to the adder ADD1.

A tuner initialization phase then begins. At the beginning of this initialization phase, the breaker of the attenuator block ATN is opened by default, activating the attenuator and the gains of the amplifiers AGCA and AGCB are by default fixed at zero. The entire signal received at the input of the signal ESO is amplified in the amplifier LNA, then attenuated in the stage ETAl. Thereafter, the signal is converted in the analog/digital converters CAN1 and CAN2.

The overall mean power of the signal is then determined as explained above and the output of the filter FIR1, representative of the deviation between this overall mean power and the reference value contained in the register MM1, decodes the table TB1. This thereby brings about the resetting of the gain of the stage ETAl (steps 20, 21 and 23). In fact, the resetting is performed only if the deviation between this overall mean power and the reference value contained in the register MM1 can be minimized (step 22), given the gain-setting possibilities provided by the stage ETAl.

More precisely, by way of example, if it is assumed that the power of the signal received at the input ESO is equal to -5 dBm. The power of the signal after amplification in the amplifier LNA having a gain of 15 dB is equal to +10 dBm. After passing through the attenuator ATN and through the amplifiers AGCA and AGCB initially adjusted to have zero gain, the overall mean power of the signal at the output of the stage ETAl is equal to -10 dBm. This power will be calculated in the digital block and compared with the first reference value which is precisely equal to -10 dBm. In this case, the deviation is zero and consequently is a

minimum value. The initialization phase then terminates and the gain and attenuation controls of the stage ETAl are thus not modified.

If, on the other hand, the power of the
5 signal received at the input ES0 is equal to -20 dBm, the power of the signal at the output of the stage ETAl is equal to -25 dBm. The calculated deviation between this overall mean power and the first reference value is then equal to -15 dBm. In this case, the means for
10 adjusting the gain of the stage ETAl can, for example, adjust the gains of the two amplifiers AGCA directly to impart a total gain of 12 dB. This will lead to the obtaining of a signal power at the output of the stage ETAl equal to -13 dBm. Given the possibilities of
15 stepwise adjustment of the amplifiers AGCA and AGCB, the deviation of -3 dB between this value and the first reference value is regarded as the minimum deviation. The initialization phase is consequently terminated.

As a variation, it will have been possible to
20 perform two successive cycles of adjustment by increasing the gain of the stage ETAl twice running in steps of 6 dB. At the end of the initialization phase, the tuner reverts to a phase of normal operation, in which the control means MCM deliver a control signal SC
25 positioning the multiplexers on their other path.

In the course of this phase of normal operation, the desired channel (step 24) is selected and the channel power is calculated in a similar manner to that described above in the block MCL (step 25).
30 The channel power is then compared and averaged with the aid of the subtractor ADD2, of the integrator FIR2 and of the second reference value stored in the memory MM2 (step 26).

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The decoding of the table TB2 allows finer adjustment of the amplifiers AGC1 and AGC2. It should be noted here that, whereas in this phase of normal operation the gain of the stage ETA1 is fixed, the gain
5 of the amplifiers AGC1 and AGC2 is constantly readjusted (step 28) so long as the calculated deviation is not regarded as a minimum (step 27).

The invention is not limited to the embodiments and modes of implementation described
10 above, but encompasses all variations thereof. Thus, the stage ETA1, although referred to generally as the attenuator/amplifier stage, could be devoid of an attenuator.

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